



### Technology Advancement for Solar Sail Propulsion (SSP) for NASA Science Missions to the Inner Solar System

A Summary Status Briefing to the Solar Sail Technology & Applications Conference

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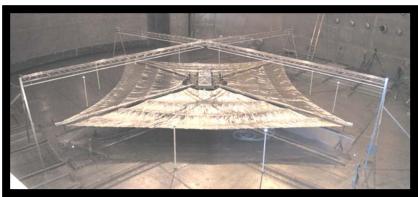
### **Contents**



### [ Solar Sail Propulsion - SSP ]

- Tech development roadmap
- Tasks funded to date
- TRL 6 Definition
- Future development plans







### **SSP Roadmap Foundations**



- Requirements Flowdown
- ♦ SSP mission statement
- mission pull
- Technology Advisory Group
- ROSS NRA



### Requirements Flowdown



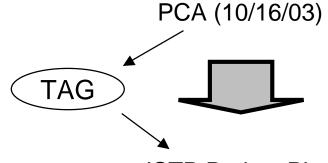


Level I – HQ/Science Mission Division



Level II – HQ (MSFC)/In-Space

**Propulsion Program** 



ISTP Project Plan

Level III – MSFC/ Solar Sail

Propulsion Technology Area



Contracts/TTAs

Level IV - Contracts & Tasks



### **SSP** Roadmap



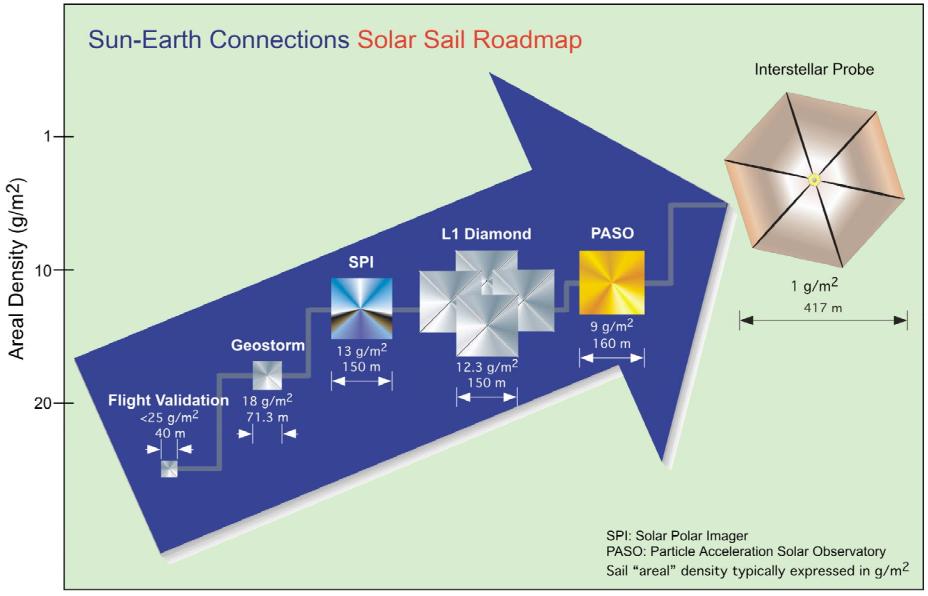
### **SSP Mission Statement (Draft Revision)**

- 1. Lower the risk of solar sail technology as a primary propulsion system to a level enabling its selection for baseline on a NASA inner solar system science mission.
- 2. Solar sail propulsion demonstration and validation shall be scalable to inner solar system NASA missions
- 3. Attain closest approach to TRL 6 possible on the ground by the end of FY06
- 4. Maximize the potential for flight validation through partnerships and collaboration.



### SSP Roadmap: Driven by Specific & Focused Mission Pull

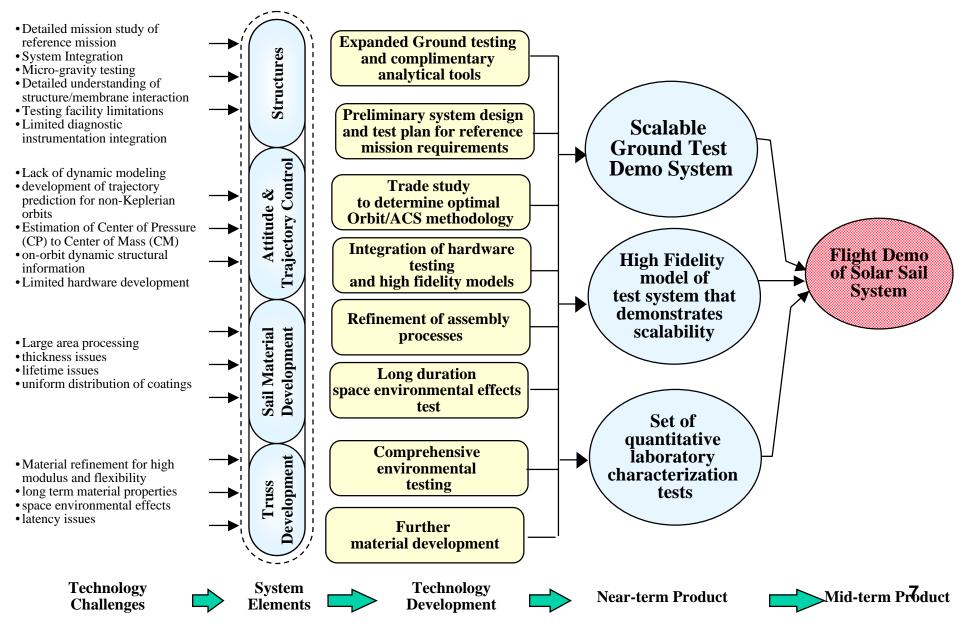






### Solar Sail Technology Assessment Group Roadmap In-Space Propulsion Program







### **Sail Technology Classes**



| Mission Class | Timeline  | SOA  | Technology Challenges  | NASA Mission<br>Application  |
|---------------|-----------|--|--|--|
| GEO/GTO       | Past/Now  | Encounter(?), Cosmos,                                  | AO, radiation belts  | None   |
| Short Life    |           | ST-7, Znamya,  | effects, high GG torques   |  |
|               |           | Inflatable Antenna Exp                                 |  |  |
| 1 Au          | Near Term | ISP Ground Demo,<br>ST-5 Geostorm<br>ST-9 SSFV         | Validation in a space environment, Infusion into mission applications                      | L1 Diamond<br>Solar Polar Imager<br>(SPI)  |
| <0.25 Au      | Mid-Term  | Mission analysis, Future ISP work                      | Materials environments, Thrust vector range, Lightweight system, 100s m system scale size  | Particle Acceleration Solar Observatory (PASO) Titan Explorer Saturn Ring Observer                     |
| Extra Solar   | Far-Term  | Mission concept<br>analysis, Gossamer,<br>Encounter(?) | Ultra-lightweight system Integrated system architecture Sub to kilometer system scale size | Interstellar Probe (ISP) Geospace System Response Imagers (GSRI) Outer Heliosphere Radio Imager (OHRI) |



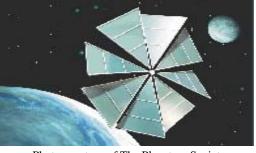
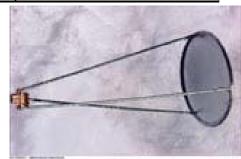


Photo courtesy of The Planetary Society

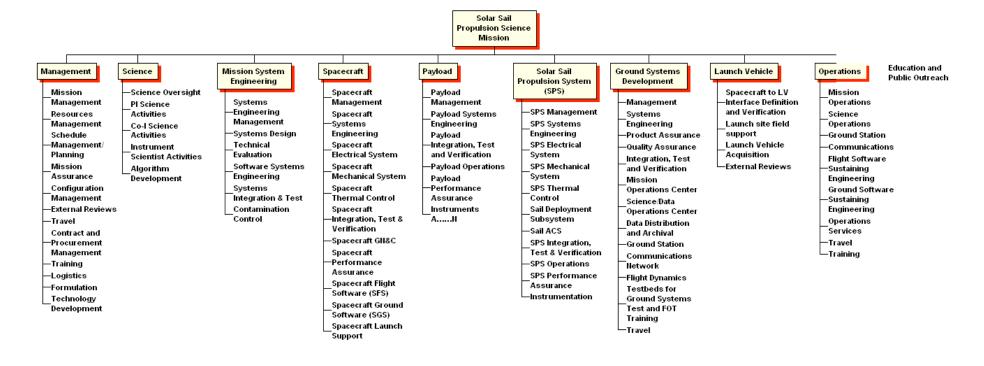






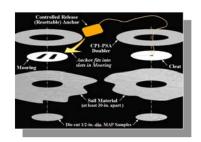
# Solar Sail Propulsion Science Mission Work Breakdown Structure









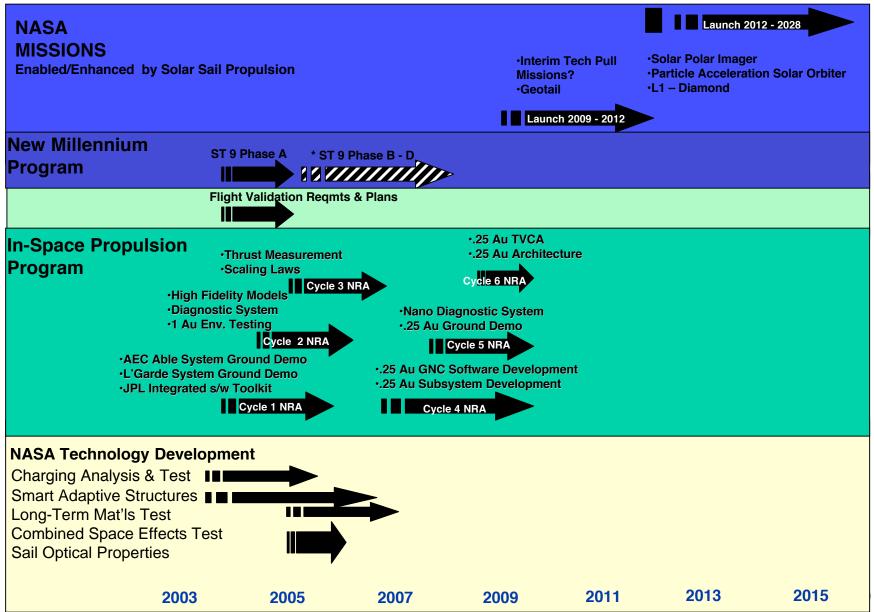






### **Solar Sail Propulsion Roadmap**







### **SSP Tasks Funded to Date**

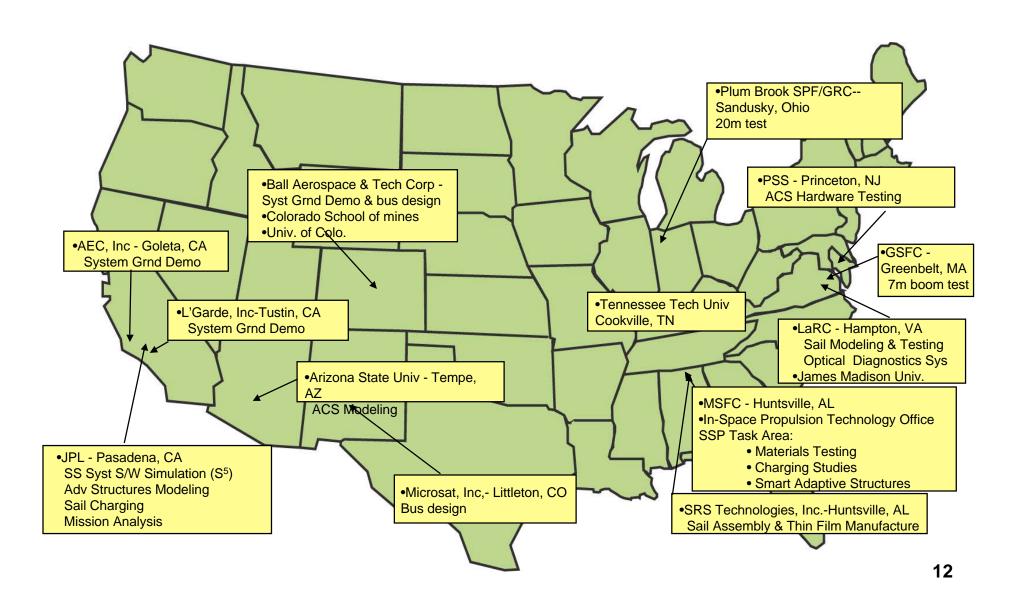


- ♦ NRA Cycles 1 & 2
- Directed Tasks
- Systems Analysis Tasks
- Composite Schedule



### **Solar Sail Propulsion Participants**









### **Funded Competed Work**



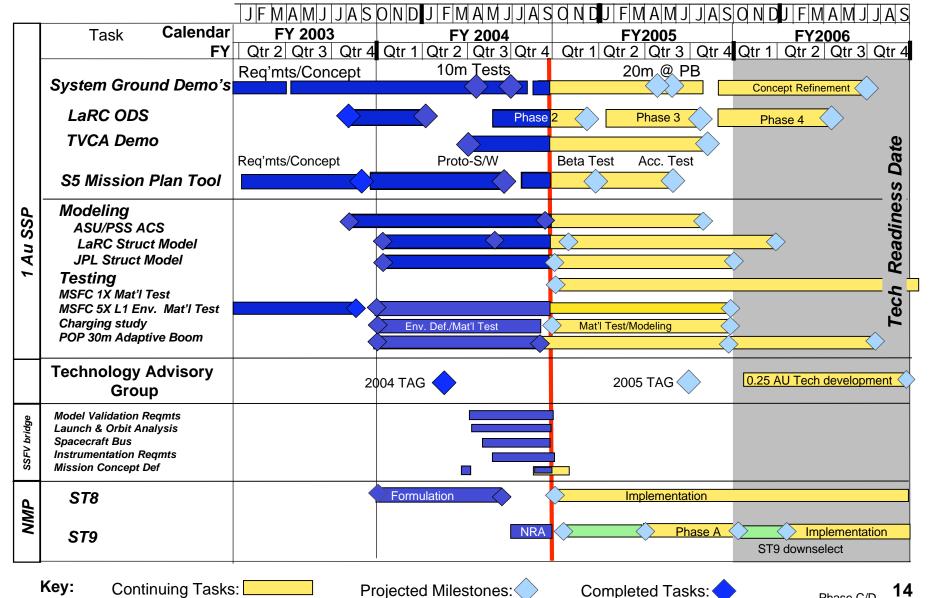
| Selection title   | Prime   |  |  |
|---|---------|--|--|
| Scalable Solar Sail System Development and Ground Demonstration | AEC     |  |  |
| Ground System Demonstrator                                      | L'Garde |  |  |
| Solar Sails GN&C Tool Kit                                       | JPL     |  |  |

| Selection title  | Prime           |
|--|-----------------|
| Optical Diagnostics System for Solar Sails   | NASA LaRC       |
| Advanced Computational Models and Software for Design and Simulation of Solar Sails Including Experimental Validation  | NASA LaRC       |
| Development of a Low-Cost, Low-Mass, Low-Volume, and Low-Power Attitude Determination and Control System (L4-ADCS) and High-Fidelity Computational Models of Solar Sail Systems                | Arizona St Univ |
| Laboratory Characterization of Candidate Solar Sail Material   | NASA MSFC       |
| Advanced Manufacturing Technologies for Solar Sails using Processes Developed Specifically for Production of Ultra-thin Solar Sail Materials for Near, Mid and Far Term Space Science Missions | SRS Tech        |
| Structural Analysis & Synthesis Tools for Solar Sails  | NASA JPL        |



#### **SOLAR SAIL PROPULSION ISP & NMP ST9 Major Milestone**







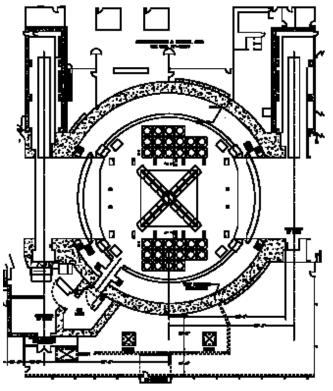
### System Ground Demos: Plum Brook 10m & 20m Layouts

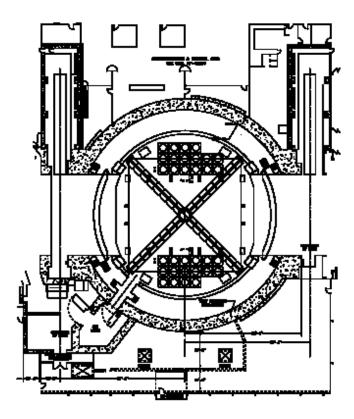




NASA Glenn Research Center, Plum Brook Station, Sandusky, Ohio

Test chamber: 30.5m (100ft) diameter by 37.2m (122ft) high







### SGDs: 10 meter tests



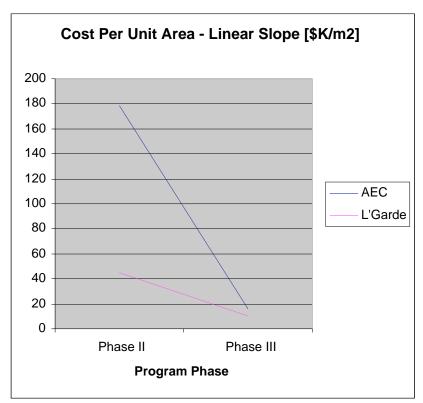
| Project Office Level 1<br>Test Requirements  | AEC  |  | L'Gard | le   |
|--|------|--|--------|--|
| Fabrication of scalable test article   | No   | Designs for 20m require features not necessary just for scaling. 20m booms require very different tip assy and deployment mechs. Sail will have ripstop and corner jumper, 10m did not. 5 micron sail was tested, 3 micron to be used. Patchwork fab/assy method to be used in phase 3 was not used in phase 2. Central structure to change significantly. Trolley needed for gravity offload. | No     | Designs for 20m require features not necessary just for scaling. Some refinements from 10 meter design needed in mandrel, gravity off-load higher off ground, line management, manufacture process, addition of a control vane to one boom (cooling, offload, viewing. Etc.), offload structure (more support form above, higher off ground, smaller avialble footpring at end of beams, boom and sail assembly process. Wrong material in UV evaluation, thermal pipe height and length must change (and not impact test instrumentation) |
| Demonstrate transportation and handling of test articles and GSE                                       | Yes  | After transport from ABLE, test articles and GSE set-up & used at LaRC. No damage identified.  | Yes    | Some wear showed on a line due to vibrations rubbing<br>Kevlar line during transport   |
| Demonstration of scalable deployment   | Part | Unexpected tear in sail in first ambient deployment attributed to sequencer. Border cord might have prevented further propagation of damage that would have affected propulsion performance or structural integrity, but test was stopped and fixed by human intervention. Later deployment was successful   | Part   | Runaway boom segment inflation and QC failure in packing lines caused half meter tear and several line failures, but not mission critical. Deployment not stopped and did continue to completion without human intervention. No successful repeat possible.  |
| Acquire adequate<br>measurements for the<br>verification of computational<br>models from test data     | Yes  | Measured gravity sag ~30% smaller than predicted. Although, the third mode shape could not be excited and a slight tweak of model to distribute spreader bar mass was required, multiple modeling results showed unusual high degree of comparison between prediction and test for deflections and mode shapes. Further analysis would be valuable.  | Part   | Boom tip cap gauges, accelerometers, videogrammetry failed. Low fidelity static deflection data from photogramemtry and dynamic data from laser vibrometer. Measured gravity sag ~30% smaller than predicted. Insufficient analysis of test data. Model frequencies close to prediction.   |
| Mechanical assy drawings<br>and electrical system<br>schematic drawing for the test<br>article and GSE | Part | Drawings made "available", but only partial set uploaded to sTIN. No drawing tree provided.  | N      | Drawings made "available", but none delivered to STIN. No drawing tree provided.   |

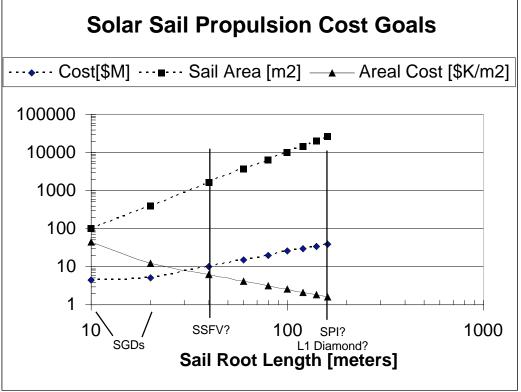


### **Technology Cost Extrapolation**



Current History – Phase II costs indicate 1 vs 4 quadrant 10 meter demonstrators Areal Costs must continue to reduce to keep total cost for science missions affordable





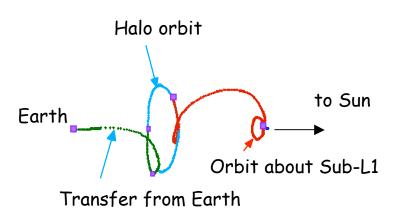
Note: Cost history is relevant to ISP-SSP system ground demonstrators



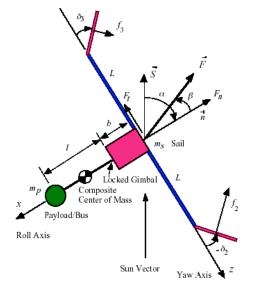
## Solar Sail GN&C Challenges



- Low Thrust Trajectories
  - Optimal Control Theory
  - Solar Sails Unique
  - Thrust Vector Constraint



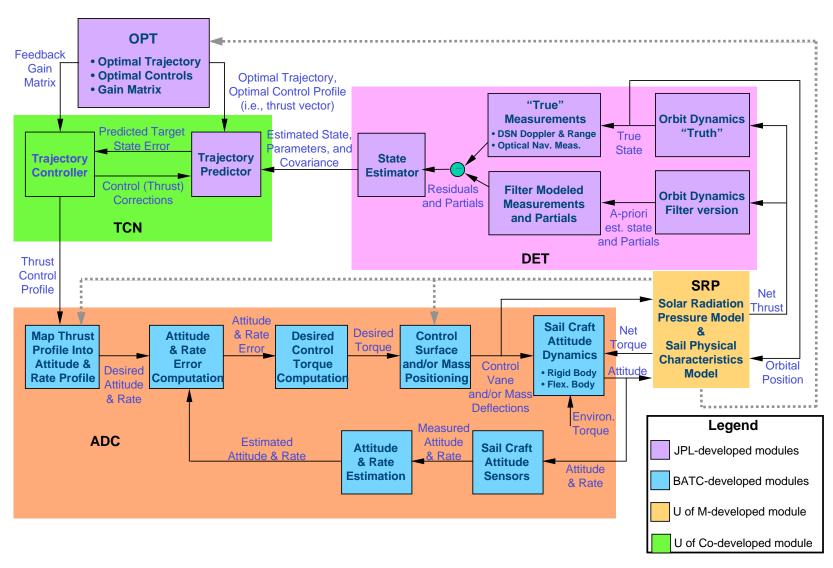
- Attitude Control Systems
  - Optical
  - CP/CM
  - Conventional





### **S5 GN&C Functional Architecture**







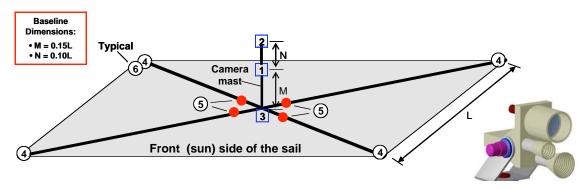
### **Optical Diagnostic System Task Summary**



#### Award for Cycle 2 Topic: Integrated Solar Sail Diagnostics Package development

#### PI: Richard Pappa, LaRC

- Ecliptic Enterprises Corporation (Pasadena, CA) data and space requirements
- South Dakota School of Mines structural models and analysis
- Texas A & M University Image processing techniques
- James Madison University Infrared thermography and fiber optic sensors
- AEC System Ground Demo Integration
- L'Garde System Ground Demo Integration



- 1 4 front-side 90-deg FOV camera clusters (16 cameras)
- 2 1 front-side inspection camera cluster with pan-tilt (3 c
- 3 4 cameras at hub, one looking down each boom (4 can
- 4 3 accelerometers at each boom tip (x & y bending, tors
- **5** Boom root strain sensors
- 6 Membrane tension sensors

#### Also:

- Infrared thermography cameras on back side mast?
- Piezoelectric actuators for dynamic excitation?





### **TRL 6 Definition**



- Origins
- Current Approach
- Potential Impacts

TRL 6: <u>Demonstration</u> of a <u>system</u> in a <u>relevant environment</u> (ground or space)



#### What is the Distinction?



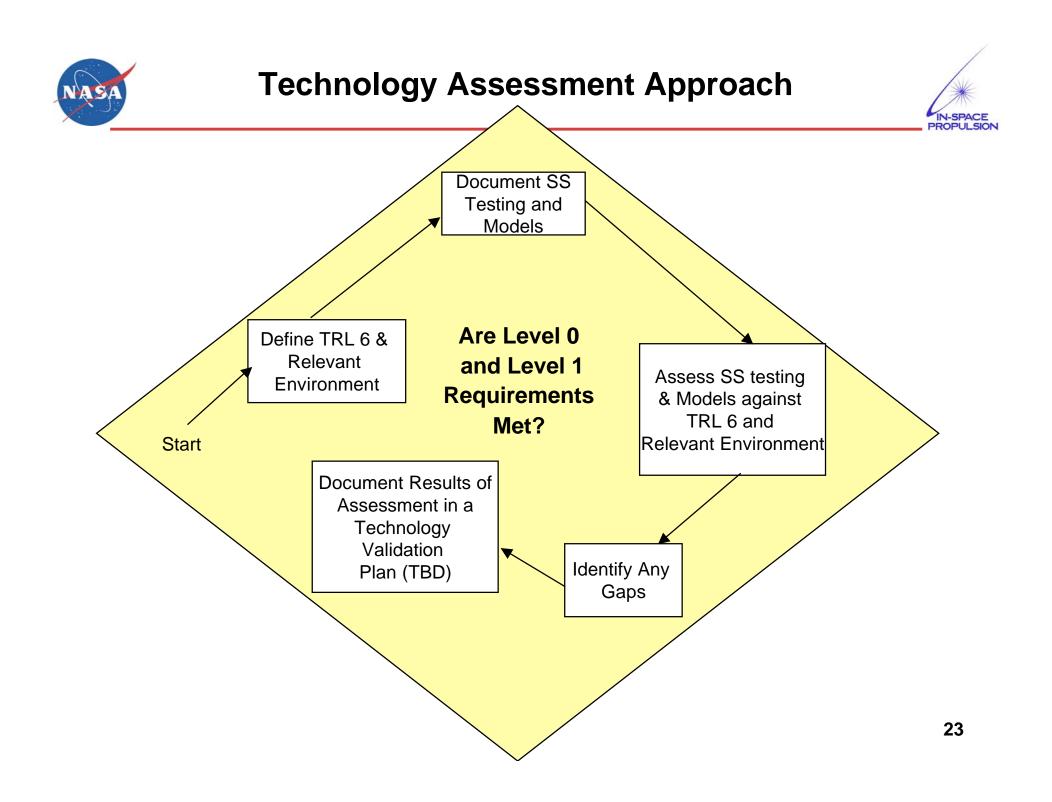
TRL 5: Component and/or breadboard validated in a relevant environment

TRL 6: System/subsystem model or prototype demonstration in a relevant environment on the ground or in space.

TRL 7: System prototype demonstrated in a space environment~

|          | Subject                                | Action        | Condition  |  |  |  |  |
|----------|--|---------------|--|--|--|--|--|
| TRL<br>5 | Component and/or breadboard            | validated     | a relevant environment                               |  |  |  |  |
| TRL      | System/subsystem<br>model or prototype | demonstration | a relevant environment on on the ground or in space. |  |  |  |  |
| 6        | System prototype                       | demonstrated  | a space environment                                  |  |  |  |  |

| TRL |                         |           |           |        |            |       |           |                    |       |
|-----|-------------------------|-----------|-----------|--------|------------|-------|-----------|--------------------|-------|
| 7   |                         | Component | Subsystem | System | Breadboard | Model | Prototype | relevant<br>ground | Space |
|     | TRL 5<br>TRL 6<br>TRL 7 |           |           |        |            |       |           |                    |       |





### **Future Plans**



### Tech Development

- NRA Cycles 3a &4
- FY05 Directed Tasks
- Systems Analysis

### Flight Validation

• NMP – ST9

#### Science Mission

- SPI
- L1 Diamond
- Interstellar Probe
- ??

### ♦ ROSS NRA Cycle 3a

- Thrust Measurement
- Scaling Laws

#### ROSS NRA Cycle 4

• TRL 6 Gaps

#### FY05 Directed Tasks

- Image Rendering for photogrammetry
- Combined Env. Effects
- Long Duration Matl'd Tetst

### Systems Analysis

- SPI Vision Mission Study
- L1 Diamond
- PASO



### **SSP Near Term Challenges**



- SSP demonstrations in simulated environments on the ground evolve concepts & capabilities well, but fall short of retiring risk for science roadmap mission applications.
  - full systems too large for conventional test methods/facilities
  - relevant environments (<10<sup>-12</sup>g, 4K, 10<sup>-6</sup>Torr) available only in space
  - full system thermal vacuum ground tests are a significant investment.
- Current SOTA is maturing rapidly
  - Mechanism designs evolving
  - Fabrication methods evolving
  - Integration with spacecraft(bus) & LV needs continued attention
  - Materials testing and charging studies so far have identified no showstoppers. Design specific issues TBD.
  - System dynamics simulation & analysis beginning
  - S5 useful immediately for trajectory design unexpected optimization may redefine sail design regmts.
  - Few unique component types flight qual at assemblies/subsystem levels



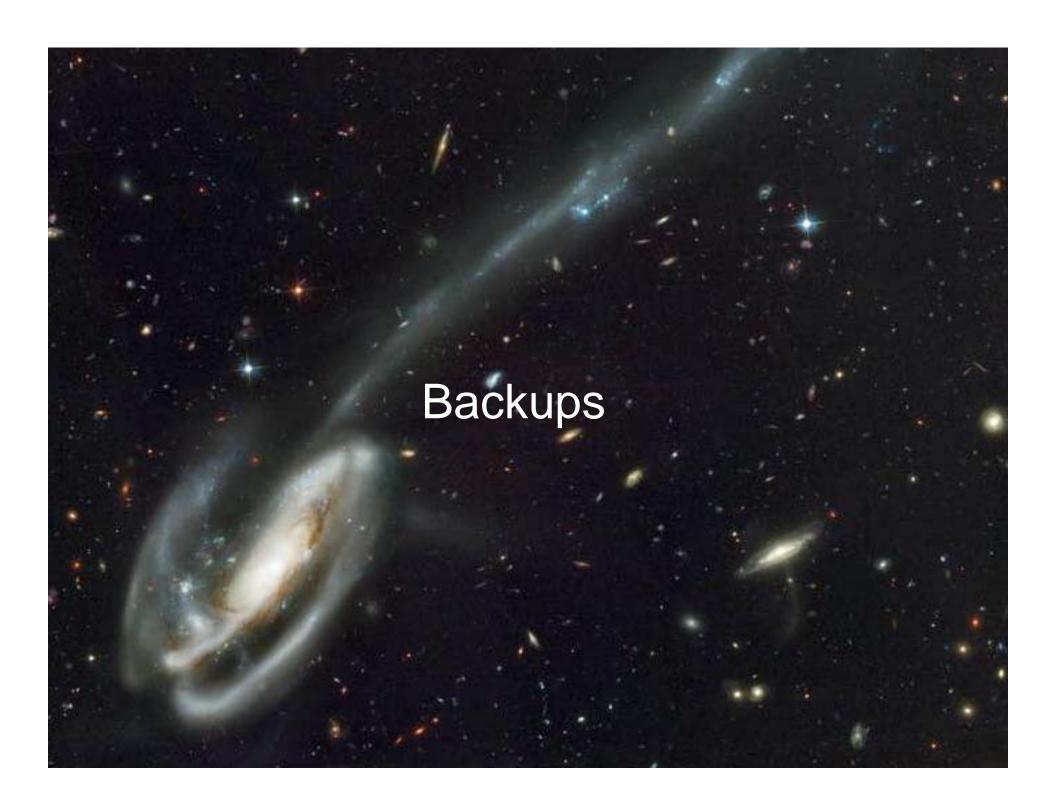




### **Solar Sail Talking Points**



- ♦ There are missions only solar sails can do--because you can't load up enough chemical propellant to do them conventionally.
- Solar Sails are environmentally friendly, safe,--and no toxic fuels or combustion byproducts, no high temperatures, or electrical currents, relatively small in size and weight.
- There is no doubt it will work--propulsion from sunlight saved a Mariner mission to Venus several decades ago. Recent advances in thin films, composites, and our understanding of how to engineer gossamer structures have made it even more practical and higher performing.
- No super-lasers or acres of unobtainium needed!
  - Sails large enough to carry people or go to destinations beyond our solar system are still in the future.
  - But there is a current need for science probes and instruments that can be done in the next very few years almost within the current SOTA.
- ♦ Solar Sail Propulsion (SSP) is the In-Space Propulsion technology activity with a goal of preparing a revolutionary alternative propulsion system for inner soilar system science missions through a program of ground development/demonstration then flight validation.
- Sails for radiation hazard sensing and communications platforms may be beneficial to new agency initiatives





### How SSP Develops Content



#### Technology Assessment Groups (TAG)

- Objectives
  - To allow technologists and system experts an opportunity to participate in an open forum to exchange information, express ideas, and provide technical insight to those responsible for developing the In-Space Propulsion technologies
  - To identify and address challenges and issues that must be overcome in order to satisfy performance, schedule and system goals to advance the technology
  - To create a technology based roadmap which captures the expertise and recommendations of the TAG participants for consideration into the project management roadmaps

#### Approach

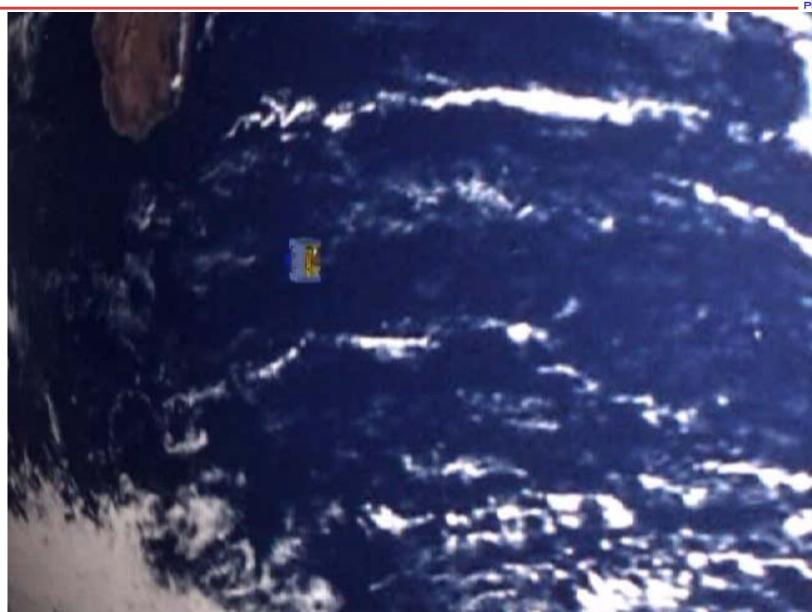
- Identify the system/subsystem level components
- Examine and determine the technology readiness level (TRL) of the current state-of-the-art technology of each subsystem
  - Access to Technical Papers and Conference Proceedings
  - Availability of unpublished test results from reputable sources
  - Participants' insight into and/or direct involvement with related research, systems analysis, and testing
- Assess the level of difficulty to advance the technology
  - Identify technology challenges (gaps)
  - Identify potential gap fillers

#### Develop Roadmap/Investment Plan and Monitor

- TAM & LSE develop/revise roadmap based on
  - Program Leadership Guidance (based on budget, Tech Prioritization, executive decisions)
  - Budget changes
  - Technology maturation
  - TAG inputs
- Reviewed monthly in HQ/FPR and MSFC/PMMR processes
- Reviewed annually in POP exercises
- Presented in Outreach Presentations (NOAA, Planetary Society, Workshops, Conferences)









# Solar Sail Propulsion Internal Management Structure



